



Controllo non lineare di circuiti per applicazioni fotovoltaiche

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Collaborazione internazionale ed industriale

Attività svolta in collaborazione con:

Bitron Industrie S.p.A.

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Universidad Nacional de Colombia



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References

PETRONE Giovanni, BIANCONI Enrico, SPAGNUOLO Giovanni, FEMIA Nicola, VITELLI Massimo, CALVENTE CALVO Francisco Javier, GIRAL CASTILLON Roberto, RAMOS PAJA CARLOS Andres:
"Metodo e dispositivo per la massimizzazione della potenza elettrica prodotta da un generatore, in particolare un generatore basato su una fonte energetica rinnovabile", brevetto italiano Bitron S.p.A., 30.07.2010, n. TO2010A000661

Enrico Bianconi, Javier Calvente, Roberto Giral, Carlos Andres Ramos Paja, Giovanni Petrone, Giovanni Spagnuolo, Massimo Vitelli:
"Improving the Perturb and Observe maximum power point tracking by using Sliding Mode Control", to be presented at IEEE ISIE 2011, Gdansk, June 2011.

Enrico Bianconi, Javier Calvente, Roberto Giral, Carlos Andres Ramos Paja, Giovanni Petrone, Giovanni Spagnuolo, Massimo Vitelli: "A fast current-based MPPT technique based on sliding mode control", to be presented at IEEE ISIE 2011, Gdansk, June 2011.

“Non-conventional” applications



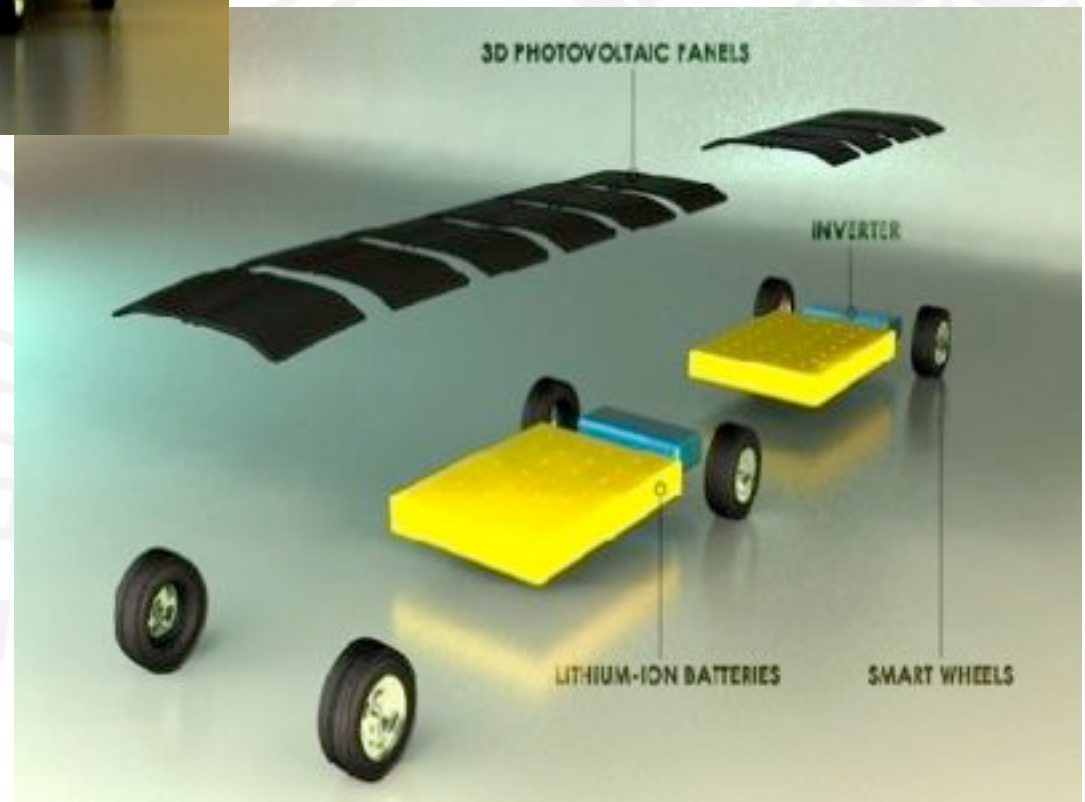
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Quickly variable shadowing

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The 'Takht Lahori' Zero-Emissions Bus

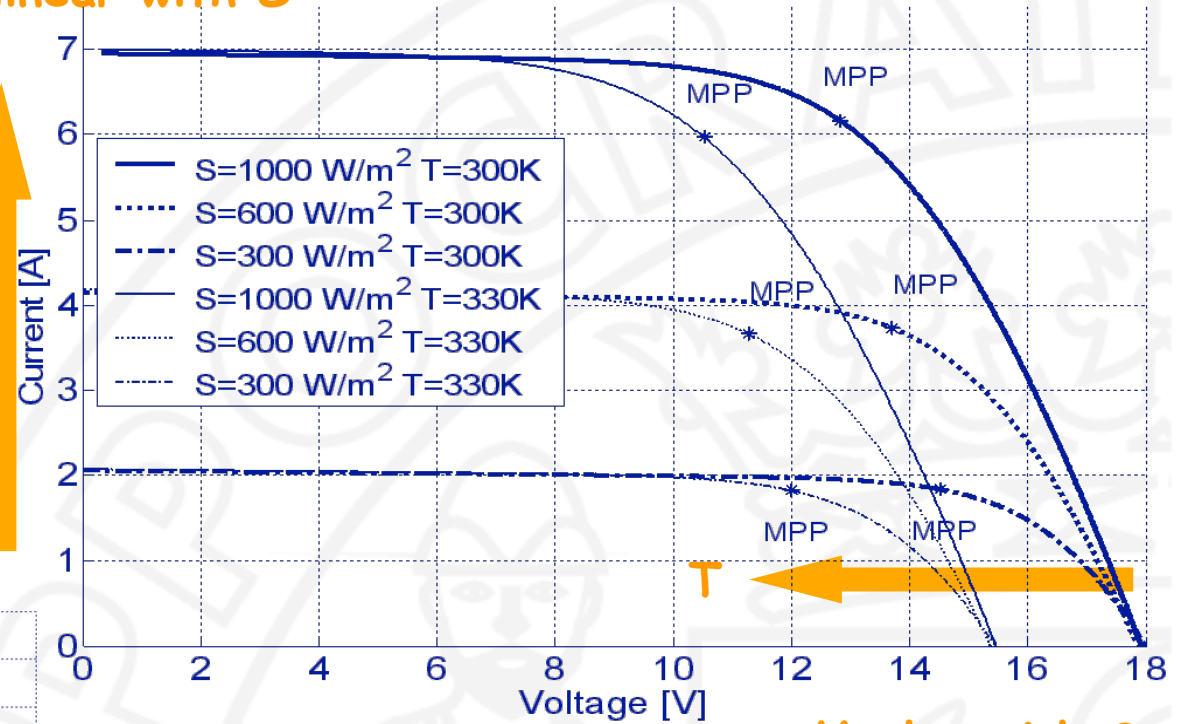


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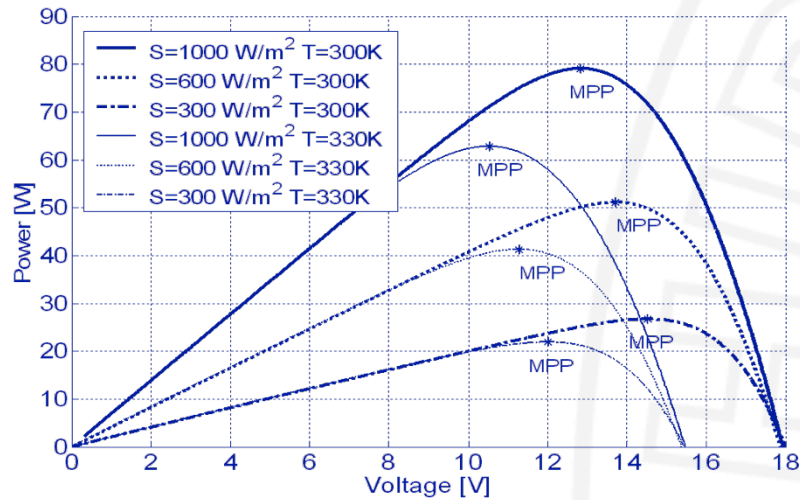
PV curves non linearity

I_{sc} linear with S

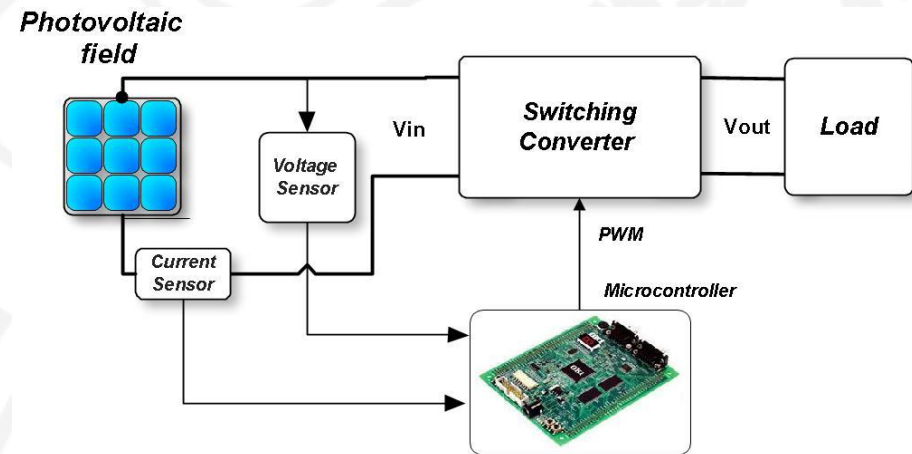
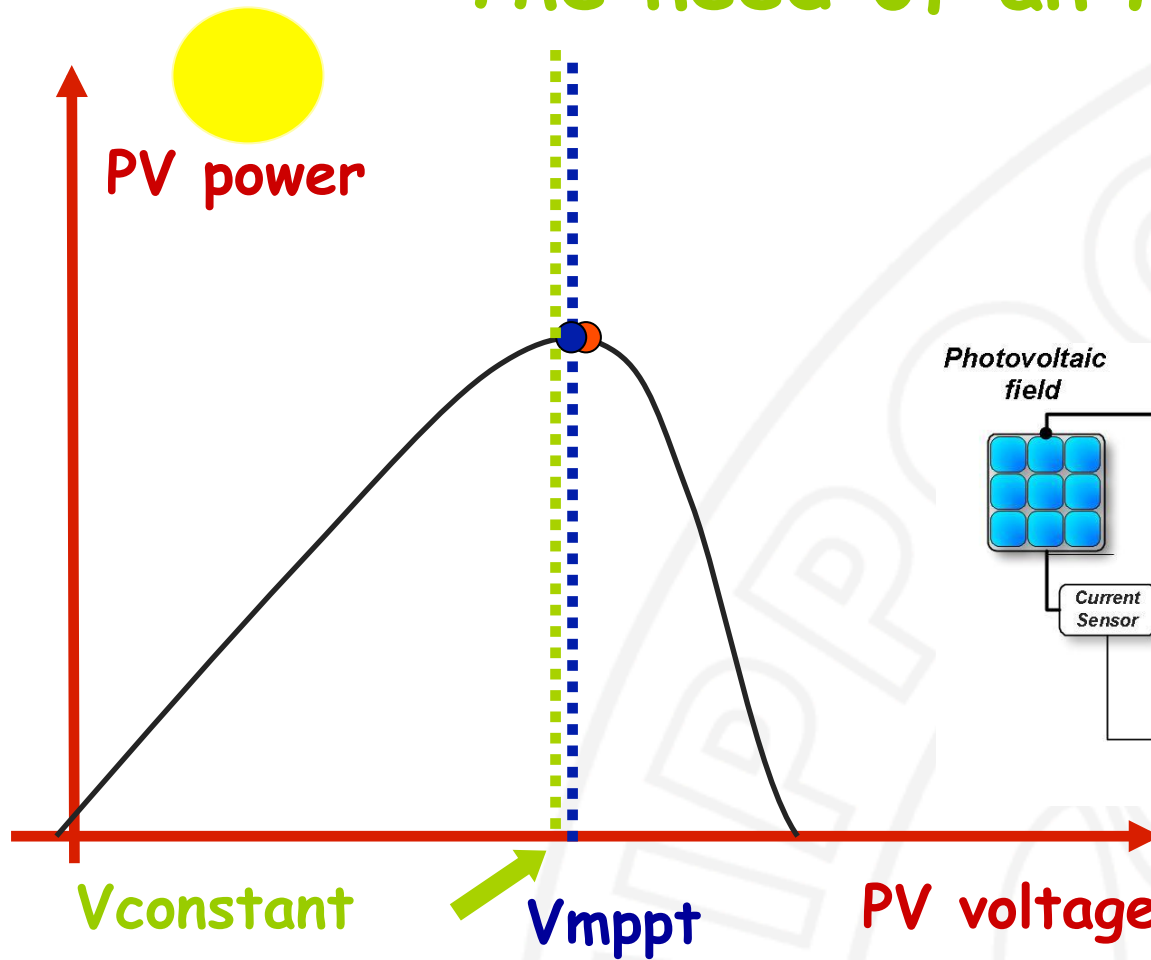
S ↑



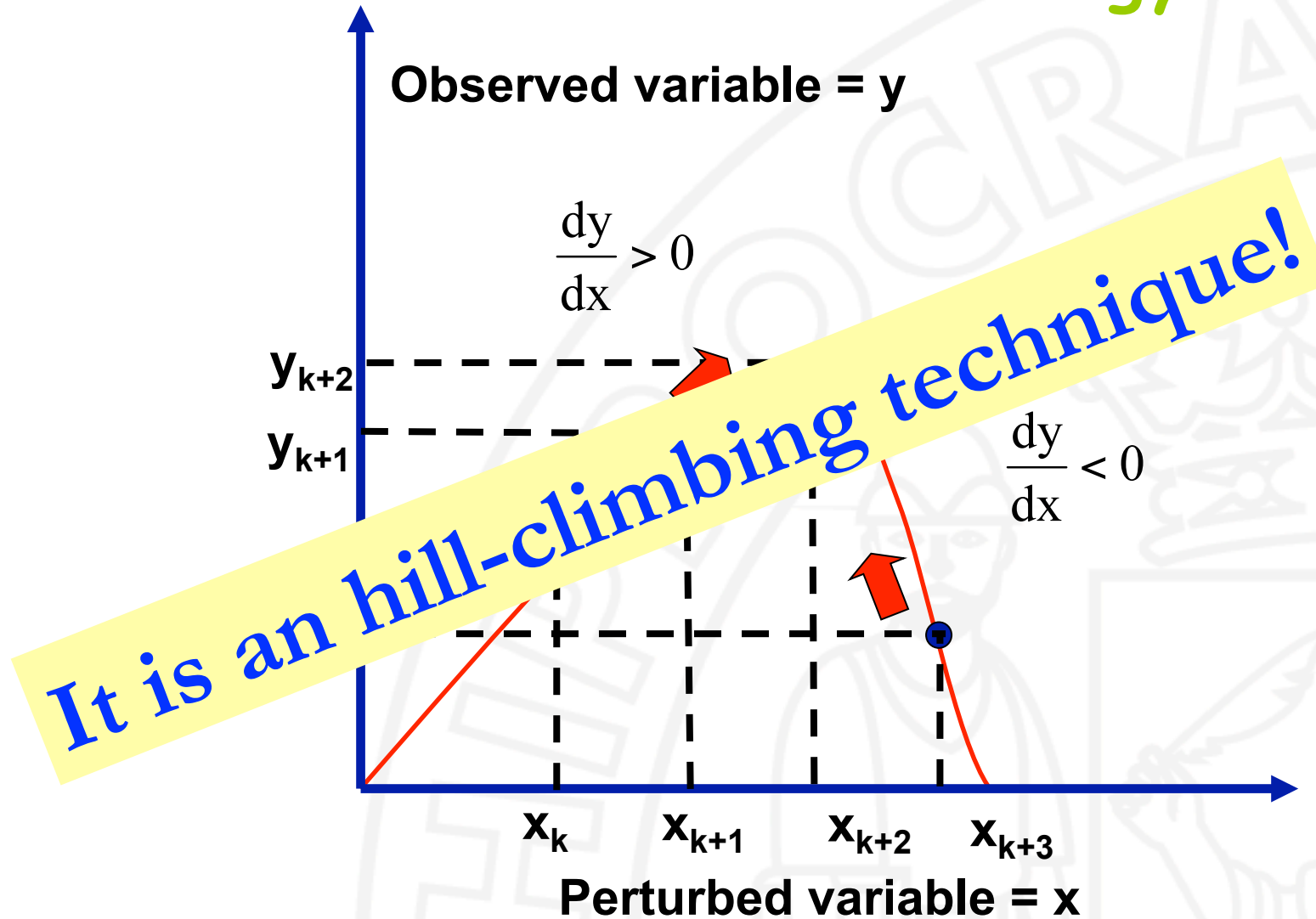
V_{oc} log with S



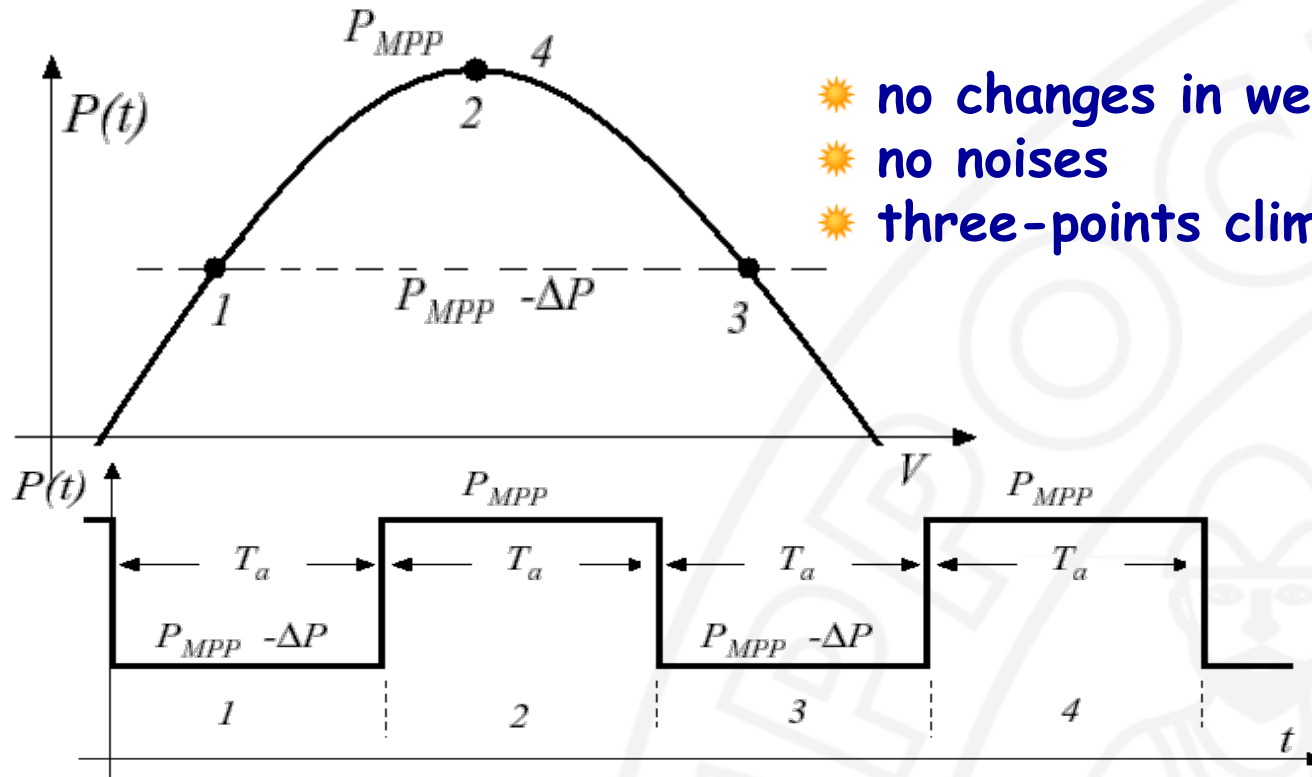
The need of an MPPT



Perturb & Observe strategy



MPPT efficiency: it is not the conversion efficiency!!!

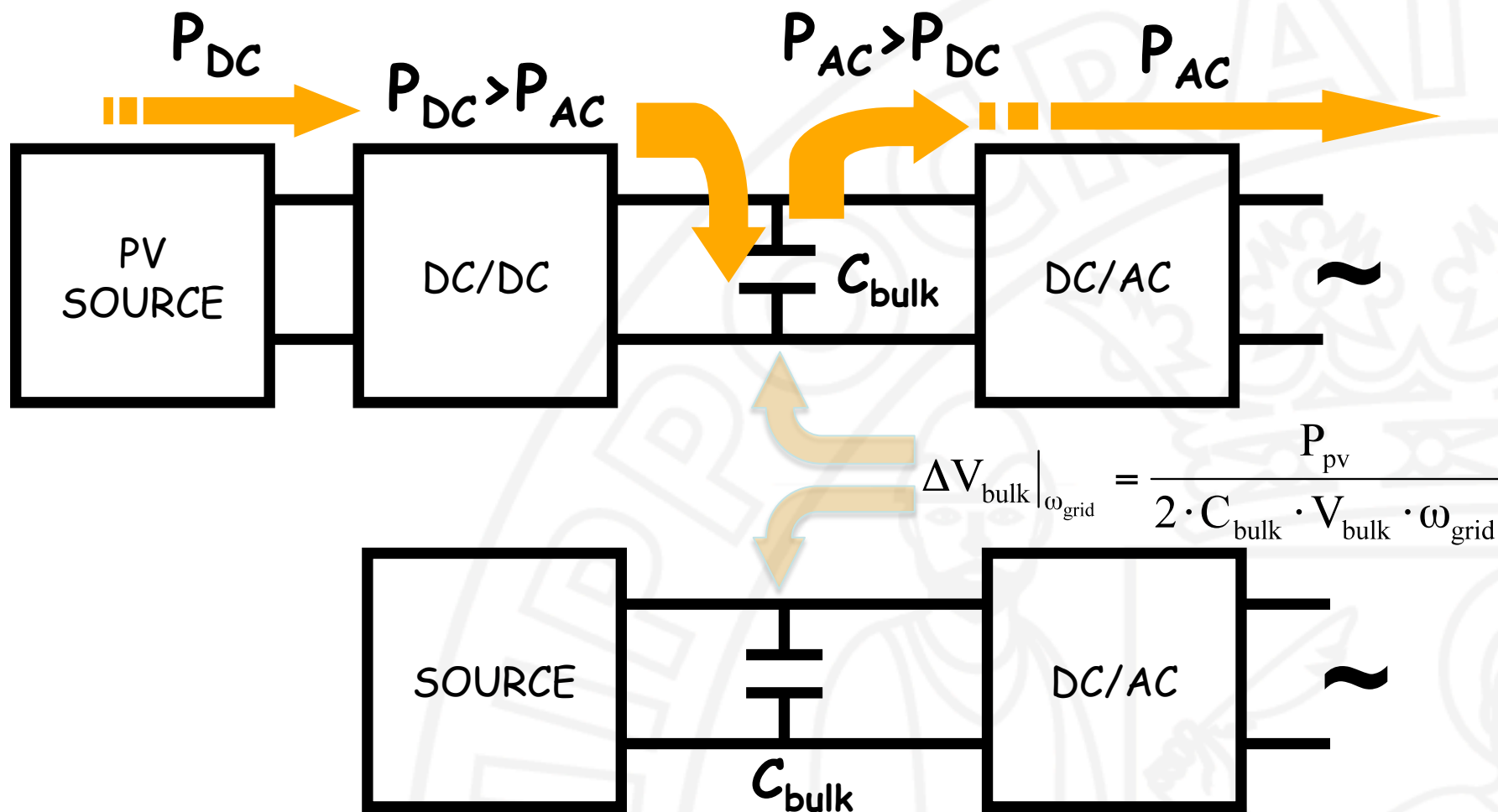


- ☀ no changes in weather conditions
- ☀ no noises
- ☀ three-points climbing (MPP included)

$$\eta_{MPPT} = \frac{\langle P(t) \rangle_{4T_a}}{P_{MPP}} = 1 - \frac{1}{2} \cdot \frac{\Delta P}{P_{MPP}}$$



Effects of AC load/grid in PV & FC

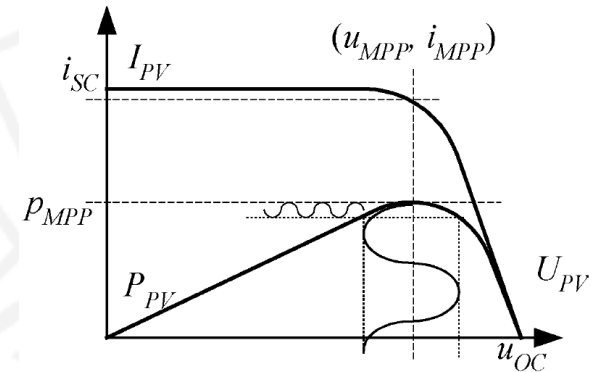


Lower C_{bulk} :

- ☺ no electrolytic capacitance C_{bulk}
- ☹ increased oscillation amplitude
- ☹ electrolytic C_{pv} might be required

Bulk voltage oscillation back-propagation

At a constant value of the dc/dc converter's duty cycle, in the MPP:



bulk voltage oscillation



Vpv oscillation



Ppv oscillation

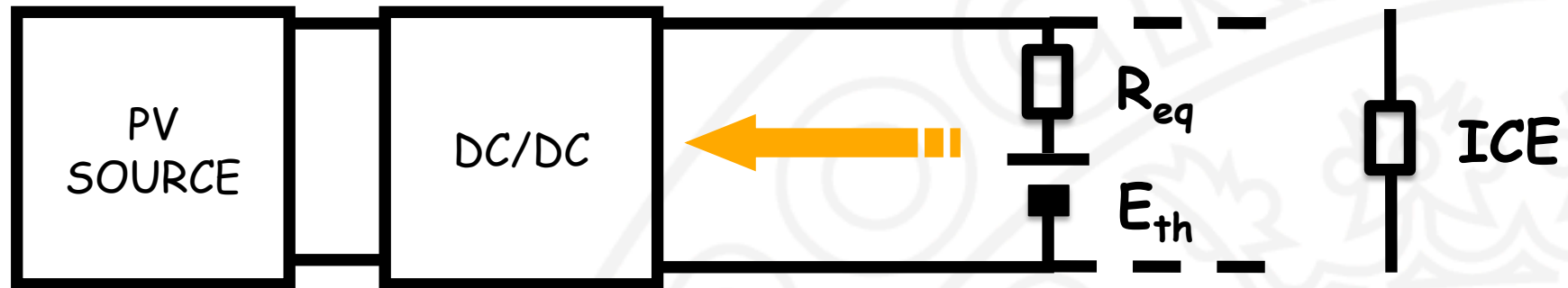


Power losses

$$\eta_{EU} = 0.03 \cdot \eta_{5\%} + 0.06 \cdot \eta_{10\%} + 0.13 \cdot \eta_{20\%} + 0.10 \cdot \eta_{30\%} + 0.48 \cdot \eta_{50\%} + 0.20 \cdot \eta_{100\%}$$

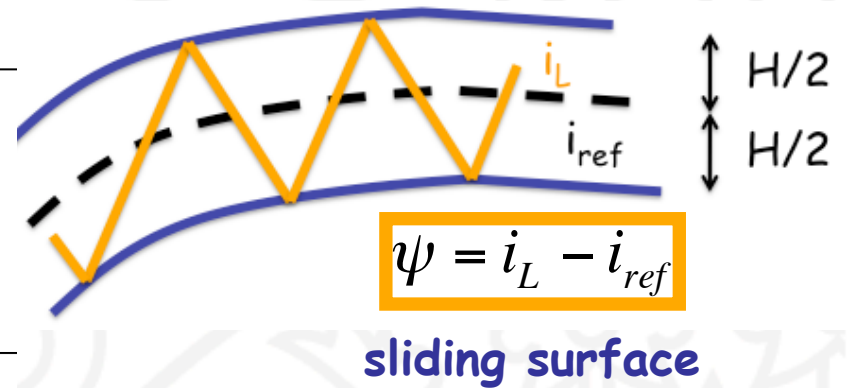
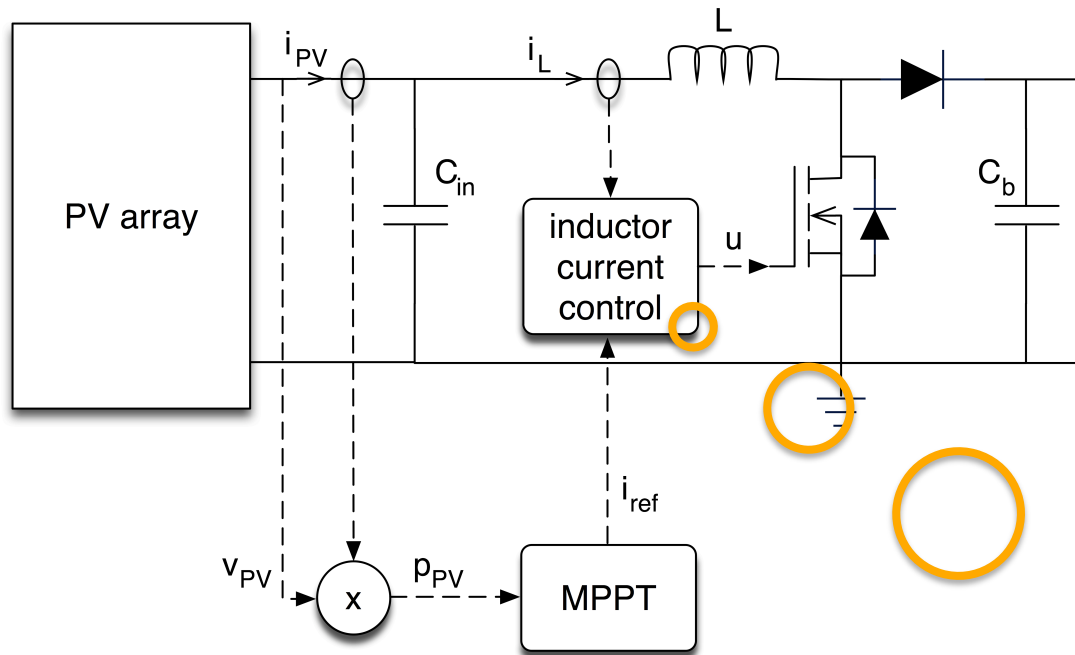
η_{EU}	$\Delta V_{\%} = \frac{\Delta V}{V_{MPP}} \cdot 100$
99.9	2.0
99.2	5.5
96.8	10.6

Effects of disturbances in off-grid systems

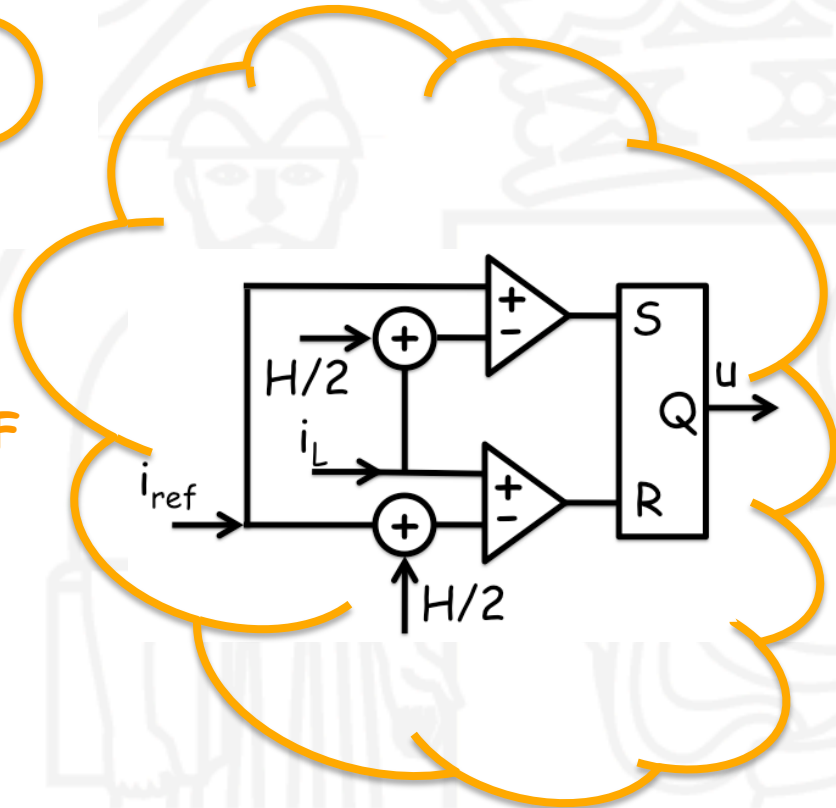


R_{eq} is significantly dependent on the battery SOC

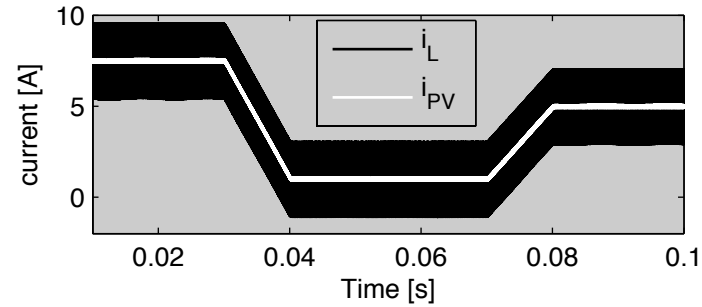
Noise reduction by sliding mode control



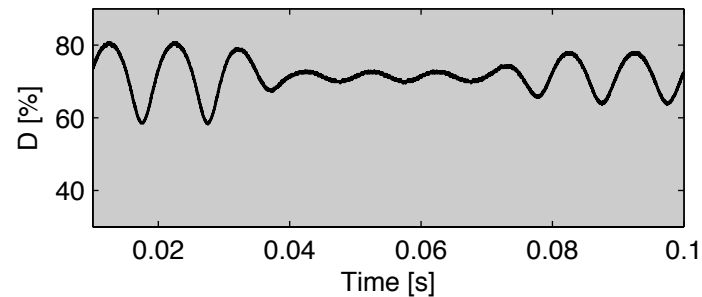
$$\begin{cases} i_L < i_{ref} - H(t)/2 & \text{mosfet turned ON} \\ i_L > i_{ref} + H(t)/2 & \text{mosfet turned OFF} \end{cases}$$



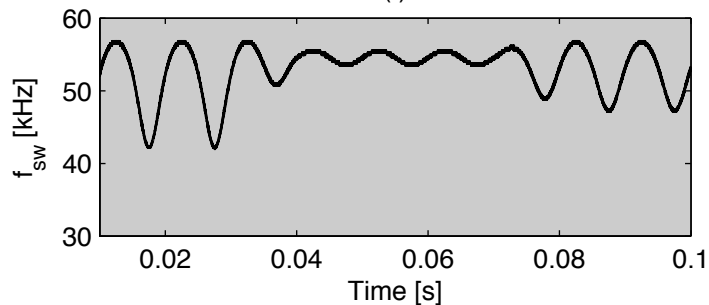
Simulation results: synchronous boost



(d)



(e)



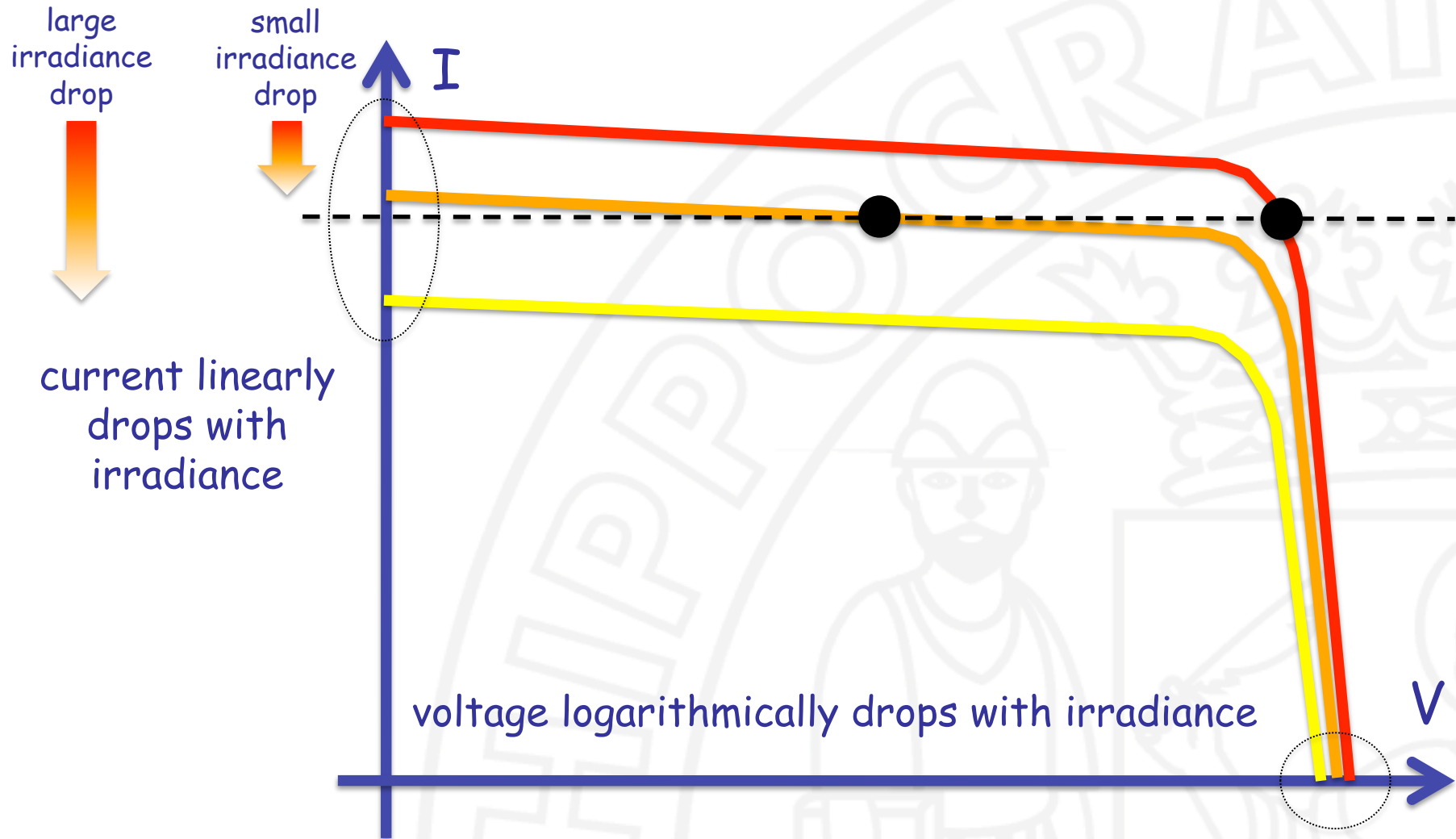
parameter	value
v_{PV}	120 V
v_{b0}	450 V
f_{grid}	50 Hz
P_{MPP}	1 kW
Δv_b	160 V
L	409 μ H
C_{in}	50 μ F
C_b	22 μ F

No disturbance affecting the inductor current

$$\Delta f_{sw}(t) = \frac{v_{PV}}{L \cdot H_0} \cdot \frac{v_{PV}}{v_{b0}} \cdot \frac{\Delta v_b(t)}{v_{b0} + \Delta v_b(t)}$$

bulk voltage oscillation amplitude

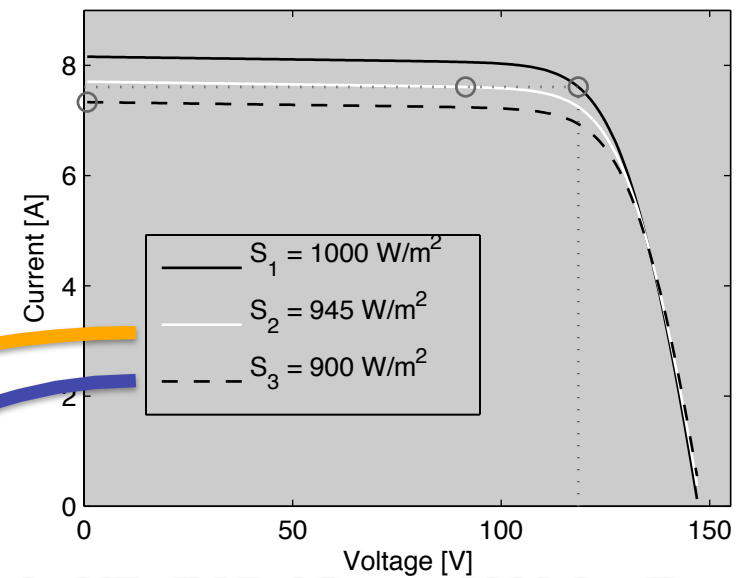
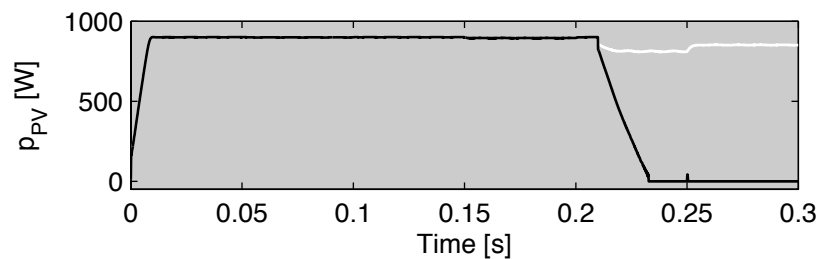
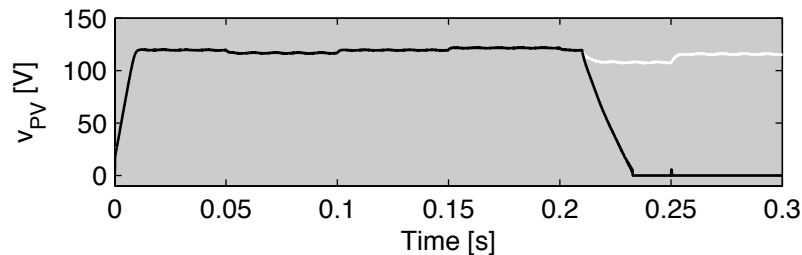
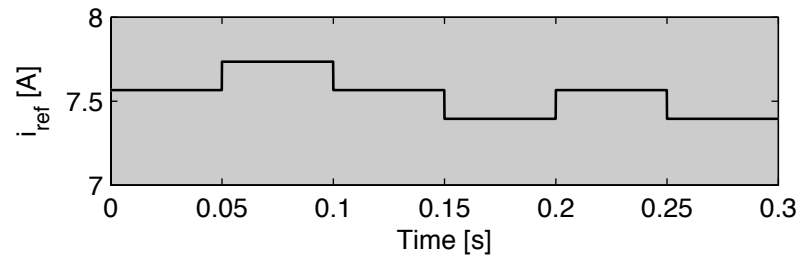
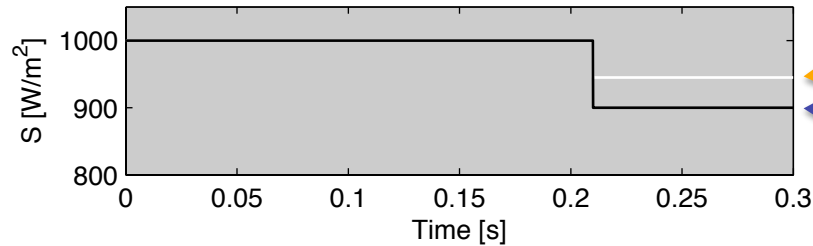
Why not current-based MPPT?



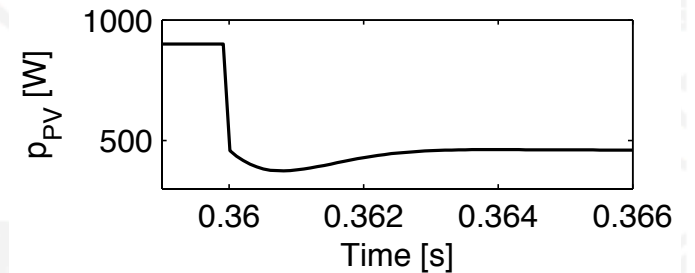
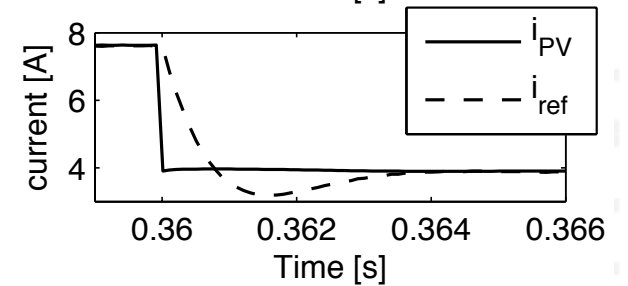
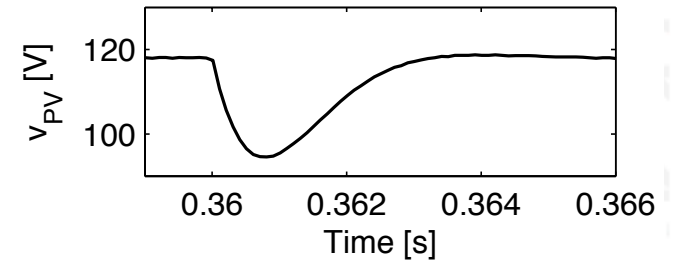
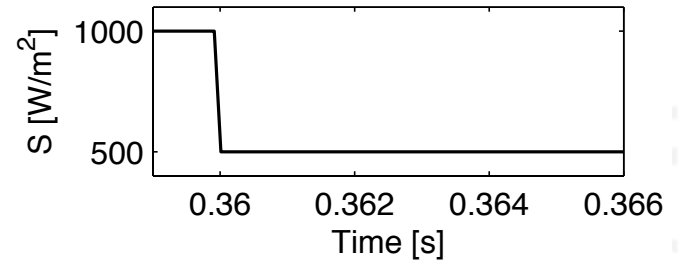
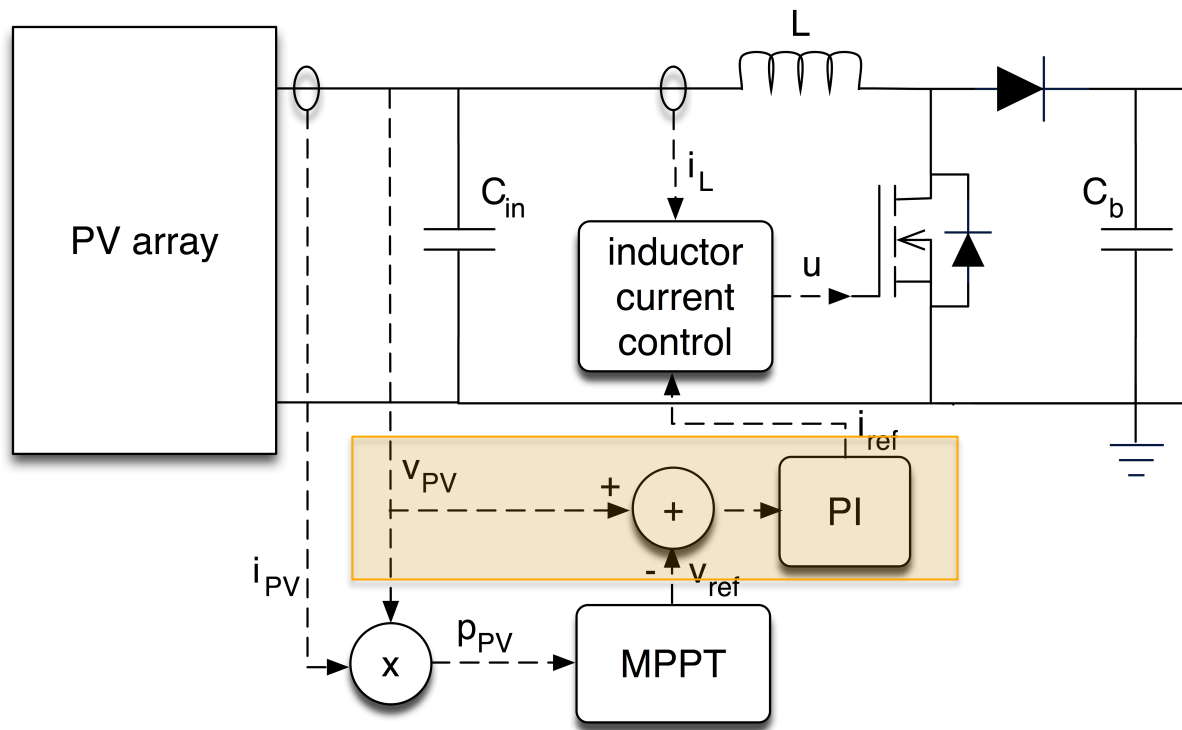
Transient performances

With a $\Delta S = 55 \text{ W/m}^2$ no problems in MPPT

With a $\Delta S = 100 \text{ W/m}^2$ the reference current is higher than the short circuit current and the upper bound $i_{\text{ref}} + H/2$ is never reached.

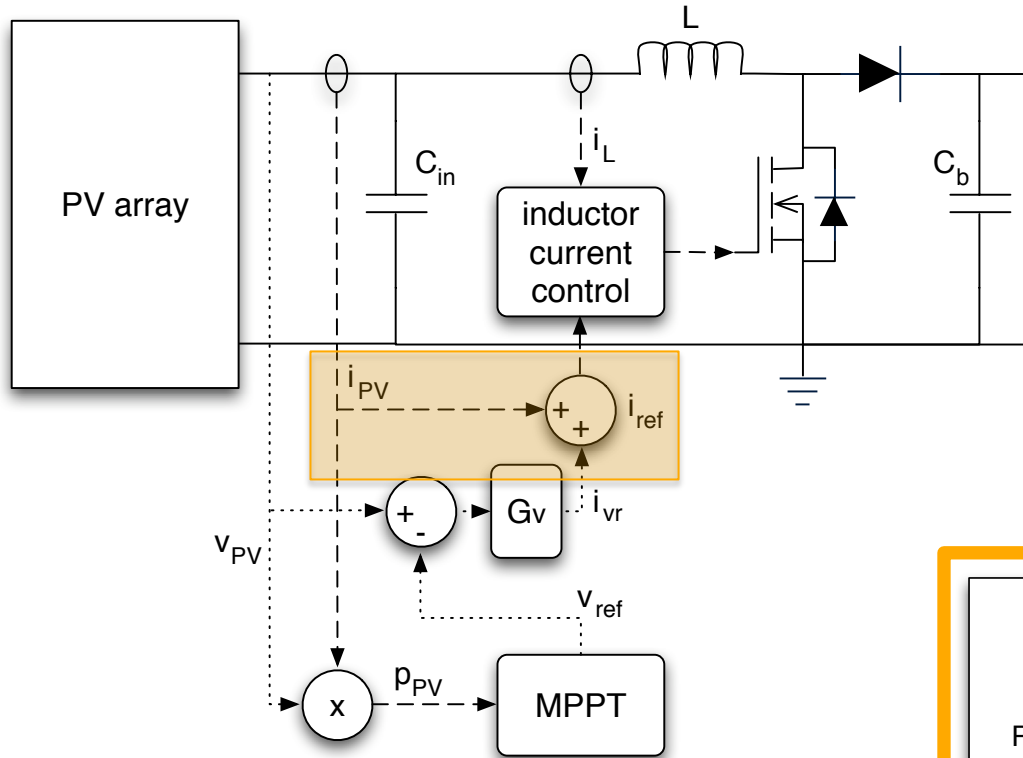


Improved MPPT performances



$$\frac{V_{pv}(s)}{I_{ref}(s)} = - \frac{R_{MPP}}{1 + R_{MPP} \cdot C_{in} \cdot s}$$

Can the MPPT promptness be improved?

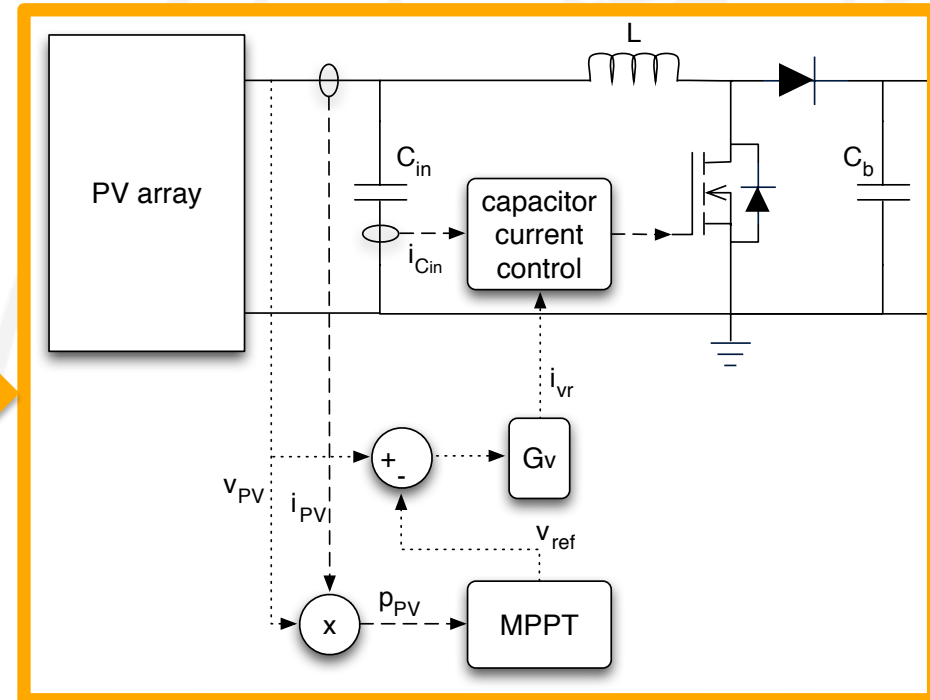


$$i_{PV} = i_{Cin} + i_L$$

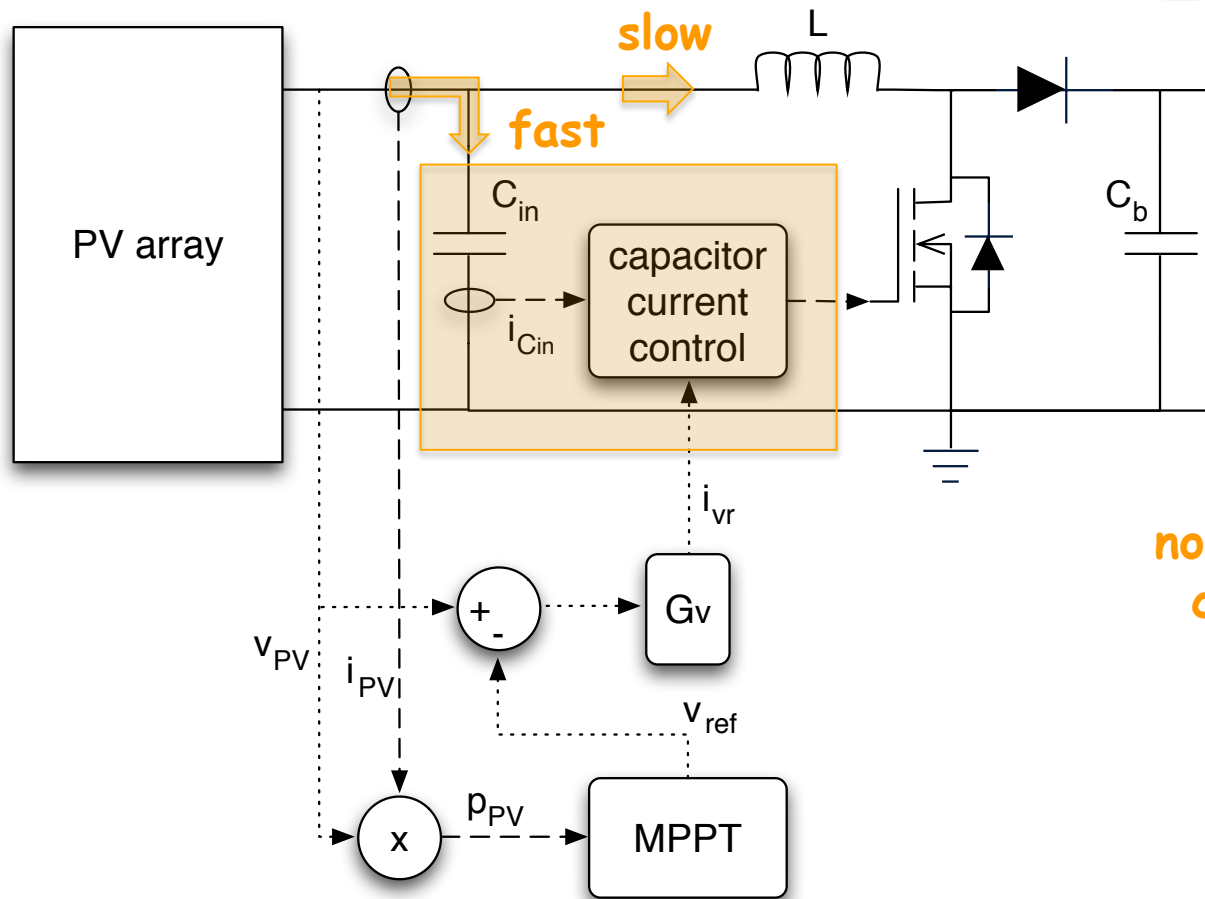
$$i_{ref} = i_{PV} + i_{vr}$$

$$e_i = i_{ref} - i_L = i_{Cin} + i_{vr}$$

$$e_i = 0 \Rightarrow i_{Cin} = -i_{vr}$$



An improved MPPT response



$$\frac{V_{pv}(s)}{I_{vr}(s)} = -\frac{1}{C_{in} \cdot s}$$

no dependency on the PV array characteristics, so that the MPPT performances do not depend on the PV array

no dependency on V_{bulk} , so that the 100Hz is rejected and the MPPT is achieved

Sliding mode conditions

$$SURF = 0$$



$$i_{Cin} + i_{vr} = 0$$



$$\frac{dv_{PV}}{dt} = -\frac{i_{vr}}{C_{in}}$$



$$\frac{V_{pv}(s)}{I_{vr}(s)} = -\frac{1}{C_{in} \cdot s}$$

$$\frac{d(SURF)}{dt} = 0$$



$$\frac{di_{Cin}}{dt} + \frac{di_{vr}}{dt} = \frac{di_{PV}}{dt} - \frac{di_L}{dt} + \frac{di_{vr}}{dt} = 0$$

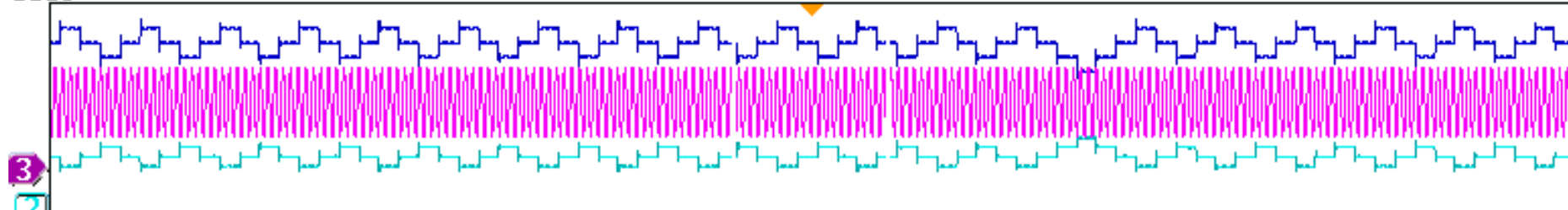


maximum
irradiation
variation that can
be tracked

Experimental results: noise effect

Tek Arres.

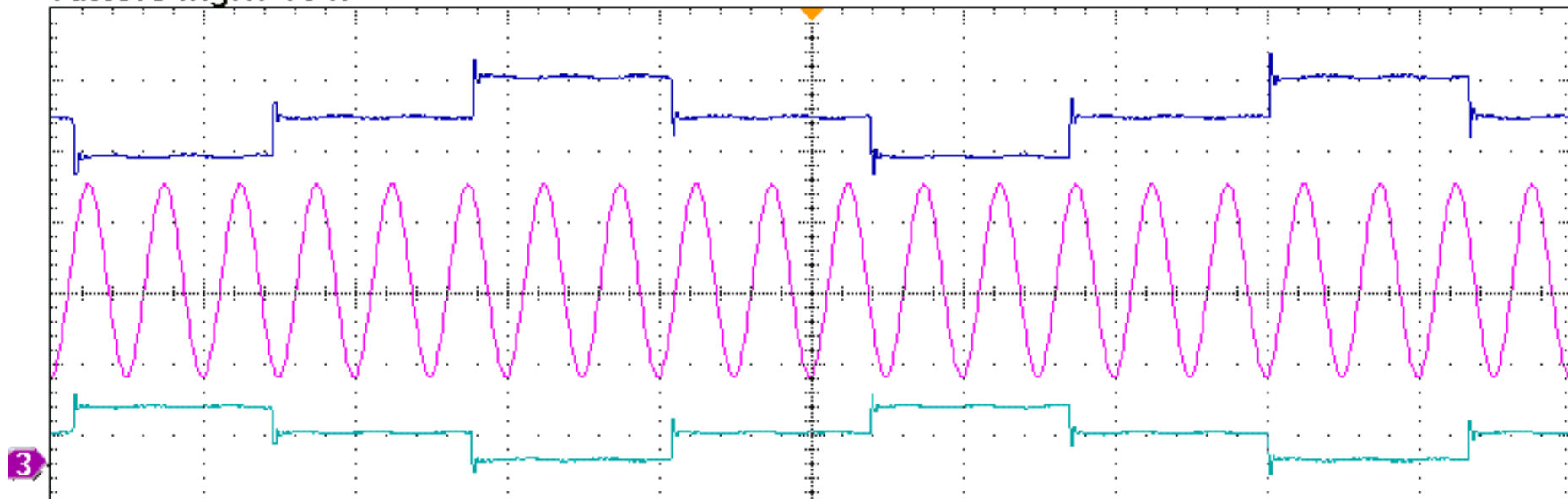
P 200ms



3

2

Fattore ingr.: 10 X



3

2

1 200mA 2 1.00 V Z 20.0ms 5.00kS/s 1 \int
3 2.00 V -624mA
 10k punti

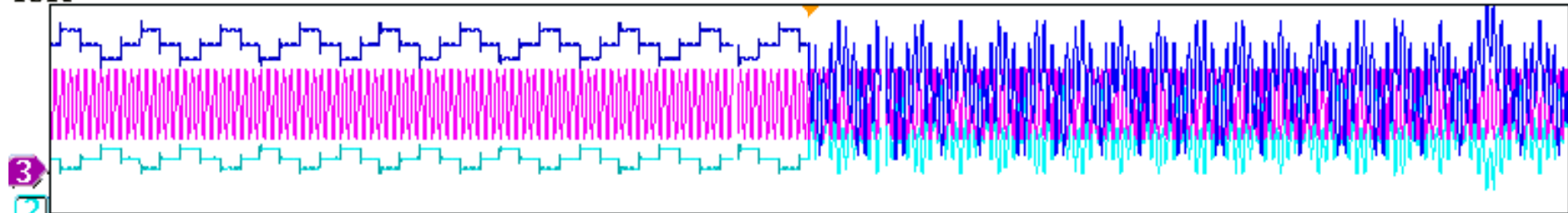
	Valore	Media	Min	Max	Dev std
3 Media	15.20 V	15.23	15.20	15.42	60.22m
2 Media	5.044 V	5.048	4.696	5.247	36.18m

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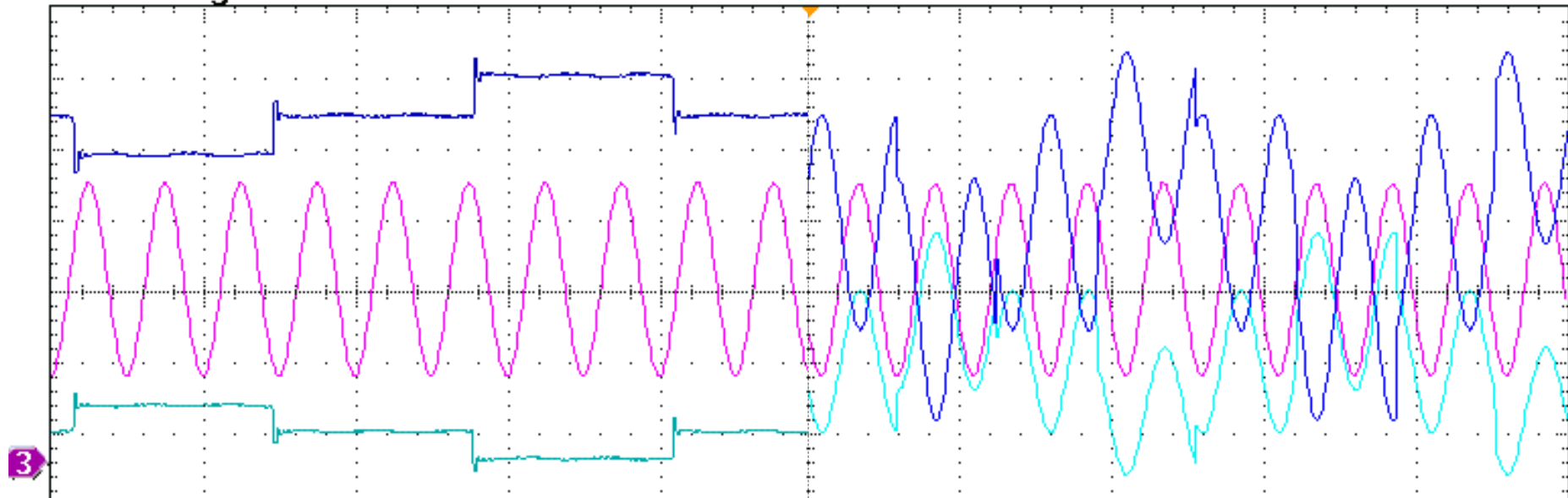
100Hz noise reduction benefit

Tek Arres.

P 200ms



Fattore ingr.: 10 X

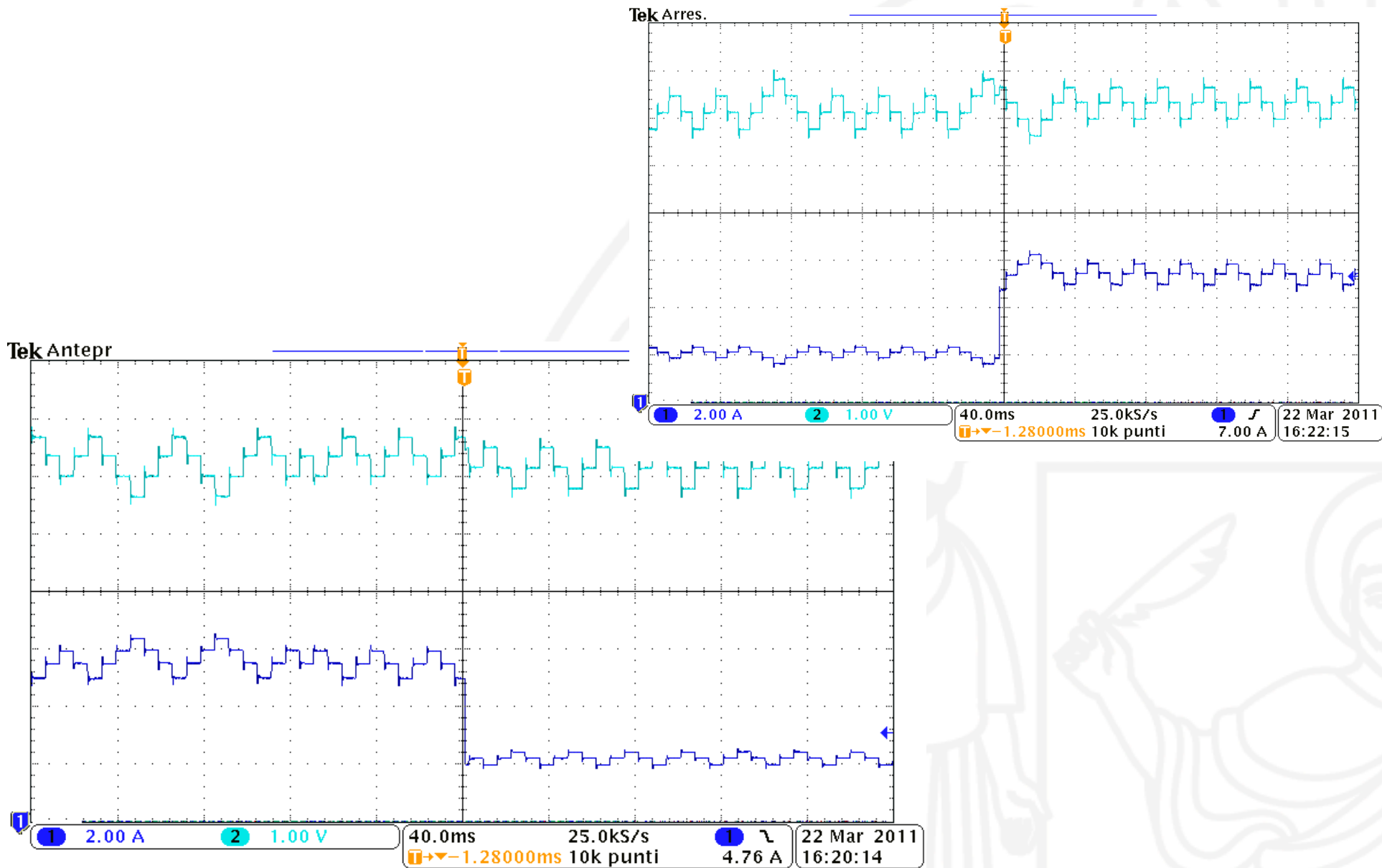


1 200mA 2 1.00 V Z 20.0ms 5.00kS/s 1 f
3 2.00 V 2 1.00 V 10k punti -624mA

	Valore	Media	Min	Max	Dev std
3 Media	15.20 V	15.23	15.17	17.71	129.9m
2 Media	5.044 V	5.048	4.698	10.75	272.6m

16 Mar 2011
14:14:21

Fast MPPT



Thank you for your attention

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